

What is claimed is:

1        1. A multi-chamber system of an etching facility for manufacturing semiconductor  
2        devices comprising:  
3                a cassette stage for mounting a cassette having wafers stacked thereon;  
4                a transfer path adjacent to the cassette stage for providing space for transportation  
5        *Sub* of wafers, the transfer path having a width slightly larger than a diameter of the wafers;  
6                a plurality of processing chambers aligned with the transfer path; and  
7                a transfer mechanism installed in the transfer path for loading and unloading the  
8        wafers stacked on the cassette stage to the plurality of processing chambers.

1        2. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 1, wherein the processing chambers are  
3        installed in multiple layers.

1        3. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 1, wherein each processing chamber has a gate  
3        formed on a side facing the transfer path, the gate being selectively opened and closed to  
4        allow passage of the wafers.

1       4. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim 1, wherein a load lock chamber is connected to  
3       one side of the processing chamber, the load lock chamber serving as a stand-by area for  
4       the wafers.

1       5. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim 4, wherein the load lock chamber comprises:  
3           a transfer arm for receiving the wafers from the transfer mechanism and  
4           transferring the wafers to the processing chamber;  
5           an inner transfer device for moving the transfer arm; and  
6           gates formed on a side of the transfer path and a side of the processing chamber,  
7           respectively, the gates being selectively opened and closed to allow passage of the wafers.

1       The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim 5, wherein the transfer arm comprises a  
3       plurality of transfer arms for simultaneously transferring a plurality of wafers.

1       7. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim 4, wherein the load lock chamber has a vacuum  
3       pressure generator for forming vacuum pressure therein.

1                   8. The multi-chamber system of an etching facility for manufacturing  
2                   semiconductor devices according to claim 4, wherein the plurality of processing chambers  
3                   have one common load lock chamber.

1                   The multi-chamber system of an etching facility for manufacturing  
2                   semiconductor devices according to claim 1, wherein processing chambers are connected  
3                   by gates such that wafers finishing one process in one processing chamber can be directly  
4                   moved to another processing chamber for a subsequent process.

1                   10. The multi-chamber system of an etching facility for manufacturing  
2                   semiconductor devices according to claim 1, wherein the processing chambers have a  
3                   vacuum pressure generator for forming vacuum pressure therein.

1                   11. The multi-chamber system of an etching facility for manufacturing  
2                   semiconductor devices according to claim 1, wherein the transfer mechanism comprises:  
3                   a transfer arm for selectively holding the wafers;  
4                   a transfer robot for loading and unloading the wafers into the processing chamber  
5                   by moving the transfer arm;  
6                   a horizontal driving part for moving the transfer robot horizontally; and

7           a controller for controlling the transfer robot and the horizontal driving part by  
8       applying control signals thereto.

1           12. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim ~~11~~, wherein the transfer mechanism further  
3       comprises a vertical driving part for moving the transfer robot vertically on receipt of a  
4       control signal from the controller.

1           13. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim 11, wherein the transfer arm is provided with a  
3       vacuum line so as to vacuum-absorb the wafers.

1           14. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim ~~11~~, wherein the transfer arm comprises a  
3       plurality of transfer arms which simultaneously transfer a plurality of wafers.

1           15. The multi-chamber system of an etching facility for manufacturing  
2       semiconductor devices according to claim ~~11~~, wherein the horizontal driving part  
3       comprises a motor or a pneumatic cylinder.

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1 16. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim 11, wherein the vertical driving part comprises  
3 a motor or a pneumatic cylinder.

1 16. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim 1, wherein the transfer path is extended and the  
3 transfer mechanism comprises a plurality of the transfer mechanisms installed so as to  
4 transfer wafers from one transfer mechanism to another.

1 16. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim 1, wherein the transfer mechanism transfers  
3 unprocessed wafers from a cassette mounted on a first cassette stage to one of the  
4 processing chambers, and processed wafers from another of the processing chambers to a  
5 second cassette stage which is located such that the wafers are easily transferred to a  
6 subsequent process.

1 16. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices of claim 1, wherein the transfer path has a rectangular shape.

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1        20. A multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices comprising:  
3                a cassette stage for mounting a cassette having wafers stacked thereon;  
4                a transfer path adjacent to the cassette stage for providing space for transportation  
5        of wafers, the transfer path having a width slightly larger than a diameter of the wafers;  
6        a plurality of processing chambers aligned in multi-layers parallel to and beside the  
7        transfer path; and  
8        6        a transfer mechanism capable of vertical/horizontal reciprocal movement installed  
9        in the transfer path for loading and unloading the wafers stacked on the cassette stage to  
10      the plurality of processing chambers.

1        21. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 20, wherein the transfer path has a rectangular  
3        shape.

1        22. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 20, wherein the multi-layers of the processing  
3        chambers number 2 to 5 layers.

1        23. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 20, wherein a load lock chamber is connected  
3        to one side of the processing chambers, the load lock chamber serving as a stand-by area  
4        for the wafers.

1        24. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 23, wherein the load lock chamber comprises:  
3            a transfer arm for receiving wafers from the transfer mechanism and transferring  
4            the wafers to the processing chamber;  
5            an inner transfer device for moving the transfer arm; and  
6            gates formed on a side of the transfer path and a side of the processing chamber,  
7            respectively, the gates being selectively opened and closed to allow passage of the wafers.

1        25. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 24, wherein the transfer arm comprises a  
3        plurality of transfer arms for simultaneously transferring a plurality of wafers.

1        26. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim 20, wherein the transfer mechanism comprises:  
3            a transfer arm having a vacuum line so as to selectively vacuum-absorb the wafers;

4 a transfer robot for loading and unloading the wafers into the processing chamber  
5 by moving the transfer arm;  
6 a vertical driving part for moving the transfer robot vertically;  
7 ~~25~~ a horizontal driving part for moving the transfer robot horizontally; and  
8 a controller for controlling the transfer robot, the vertical driving part, and the  
9 horizontal driving part by applying control signals thereto.

1 ~~25~~ 27. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim ~~26~~ 28, wherein the transfer arm comprises a  
3 plurality of the transfer arms which simultaneously transfer a plurality of wafers.

1 ~~26~~ 28. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim ~~26~~ 28, wherein the vertical driving part and the  
3 horizontal driving part each comprise a motor or a pneumatic cylinder.

1 ~~27~~ 29. The multi-chamber system of an etching facility for manufacturing  
2 semiconductor devices according to claim ~~26~~ 28, wherein the transfer path is extended, and  
3 the transfer mechanism comprises a plurality of transfer mechanisms installed so as to  
4 transfer wafers from one transfer mechanism to another.

1        20. The multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices according to claim ~~20~~, wherein the transfer mechanism transfers  
3        unprocessed wafers from a cassette mounted on a first cassette stage to one of the  
4        processing chambers, and processed wafers from another of the processing chambers to a  
5        second cassette stage which is located such that the wafers are easily transferred to a  
6        subsequent process.

1        31. A multi-chamber system of an etching facility for manufacturing  
2        semiconductor devices comprising:  
3                a first cassette stage for mounting a cassette having unprocessed wafers stacked  
4                thereon;  
5                a transfer path adjacent to the first cassette stage, the transfer path having a  
6                rectangular shape and providing a space for transportation of wafers;  
7                a plurality of processing chambers arranged in multi-layers and aligned in parallel  
8                beside the transfer path;  
9                a transfer mechanism capable of vertical/horizontal reciprocal movement installed  
10                in the transfer path for loading and unloading the wafers stacked on the first cassette stage  
11                to the plurality of processing chambers; and  
12                a second cassette stage placed opposite to the first cassette stage and mounting a  
13                cassette having processed wafers stacked thereon.

1           32. The multi-chamber system of an etching facility for manufacturing  
2           semiconductor devices according to claim 31, wherein the transfer mechanism comprises:  
3           a transfer arm having a vacuum line for selectively vacuum-absorbing wafers;  
4           a transfer robot for loading and unloading wafers to the processing chambers by  
5           moving the transfer arm;  
6           a vertical driving part for vertically moving the transfer robot;  
7           a horizontal driving part for horizontally moving the transfer robot; and  
8           a controller for controlling the transfer robot, the vertical driving part, and the  
9           horizontal driving part by applying control signals thereto.